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Estimated student time to complete: 20 minutes Prerequisite knowledge required: Text Section(s) 3.10 Solution: The robot has 6 revolute joints. From Equation 3.26: $T_6^1 = \begin{pmatrix} -n_x p_y + n_y p_x \\ \dots \end{pmatrix}$ where for $i=6$ we use $5T_6 = A_6$ given in Equation 2.57.

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