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The team engineered the robot as simply a torso and two legs, and designed the system specifically to test lower-body tasks, such as

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Artificial Intelligence. As with its full-body counterpart, Little HERMES is designed for teleoperation, with an operator suited up in a vest to control the robot's actions.

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could benefit from it for approaching the field of legged robots (and their control problems), for ...

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types, whether flat or uneven, is very important for a wide range of service operations in robotics. Potential applications range from surveillance, rescue, or hospital assistance.

Wheeled-legged hexapod robots have been designed to solve these locomotion tasks. Given the wide

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range of feasible operations, one of the key operation planning issues is related to ...

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Abstract—The ability of legged systems  
to traverse highly-constrained

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environments depends by and large on the performance of their motion and balance controllers. This paper

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